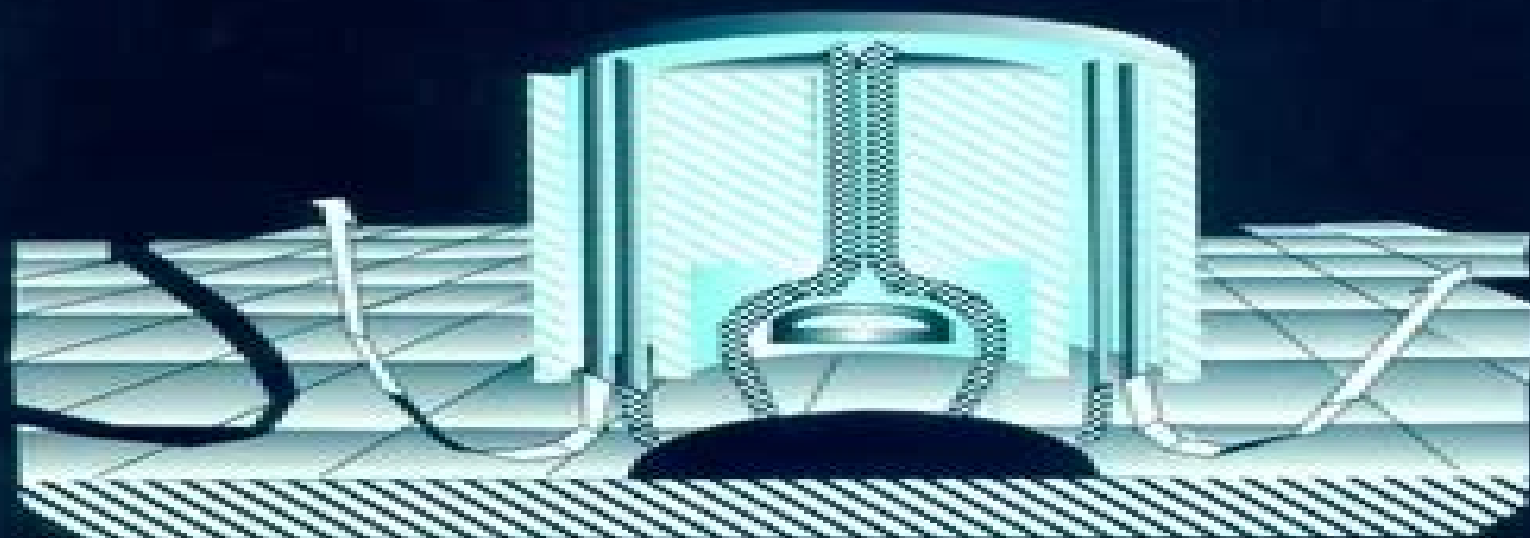


World Scientific Series in Robotics and Intelligent Systems – Vol. 22

ODOUR DETECTION BY MOBILE ROBOTS

R. ANDREW RUSSELL



World Scientific

Odour Detection By Mobile Robots

JL Elias

A decorative graphic element consisting of a horizontal light blue bar with a rounded right end, overlapping a red circular gradient that fades out to the right.

Odour Detection By Mobile Robots:

Odour Detection By Mobile Robots Andrew R Russell,1999-03-19 Insects are extremely successful creatures thriving in our ever changing and unpredictable world One of the factors behind their success is the use of odour to increase their efficiency when searching for food to help navigate between a source of food and their nest and to enable them to find a mate Mobile robots would have their capabilities greatly enhanced if they could make use of similar techniques This important book describes current research aimed at giving robots the ability to generate detect and discriminate between odours together with the control algorithms using such sensory information Odour Detection by Mobile Robots R. Andrew Russell,1999 Insects are extremely successful creatures thriving in our ever changing Odour Sensing Technology Odour Discrimination Airflow Broadcast Chemical Signals Chemical Markings as Signals Trail Following Coding Information into Trails Heat as a Short Lived Marker Readership Graduate students researchers in robotics mechatronics artificial intelligence Active Sensors for Local Planning in Mobile Robotics Penelope Probert Smith,2001 This book describes recent work on active sensors for mobile robots An active sensor interacts with its surroundings to supply data on demand for a particular function gathering and abstracting information according to need rather than acting as a generic data gatherer Details of the physical operation are hidden The book deals mainly with active range sensors which provide rapid information for local planning describing extraction of two dimensional features such as lines corners and cylinders to reconstruct a plan of a building It is structured according to the physical principles of the sensors since to a large extent these determine the function of the sensors and the methods of processing Recent work using sonar optoelectronic sensors and radar is described Sections on vision and on sensor management develop the idea of software adaptation for efficient operation in a changing environment Contents The Mapping and Localisation Problem Perception at Millimetre Wavelengths Advanced Sonar Principles of Operation and Interpretation Smooth and Rough Target Modelling Examples in Mapping and Texture Classification Sonar Systems A Biological Perspective Map Building from Range Data Using Mathematical Morphology Millimetre Wave Radar for Robotics Optoelectronic Range Sensors AMCW LIDAR Range Acquisition Extracting Lines and Curves from Optoelectronic Range Data Active Vision for Mobile Robot Navigation Strategies for Active Sensor Management Readership Graduate students and final year undergraduate students in electrical and electronic engineering systems and knowledge robotics image processing and artificial intelligence **Adaptive Mobile Robotics - Proceedings Of The 15th International Conference On Climbing And Walking Robots And The Support Technologies For Mobile Machines** Mohammad Osman Tokhi,Noah J Cowan,Abul K M Azad,Gurvinder S Virk,Roger D Eastman,2012-07-11 This book provides state of the art scientific and engineering research findings and developments in the area of mobile robotics and associated support technologies The book contains peer reviewed articles presented at the CLAWAR 2012 conference Robots are no longer confined to industrial manufacturing environments A great deal of interest is invested in the

use of robots outside the factory environment The CLAWAR conference series established as a high profile international event acts as a platform for dissemination of research and development findings and supports such a trend to address the current interest in mobile robotics to meet the needs of mankind in various sectors of the society These include personal care public health services in the domestic public and industrial environments The editors of the book have extensive research experience and publications in the area of robotics in general and in mobile robotics specifically and their experience is reflected in editing the contents of the book *Adaptive Mobile Robotics* Abul K. M. Azad,2012 This book provides state of the art scientific and engineering research findings and developments in the area of mobile robotics and associated support technologies The book contains peer reviewed articles presented at the CLAWAR 2012 conference Robots are no longer confined to industrial and manufacturing environments A great deal of interest is invested in the use of robots outside the factory environment The CLAWAR conference series established as a high profile international event acts as a platform for dissemination of research and development findings and supports such a trend to address the current interest in mobile robotics to meet the needs of mankind in various sectors of the society These include personal care public health services in the domestic public and industrial environments The editors of the book have extensive research experience and publications in the area of robotics in general and in mobile robotics specifically and their experience is reflected in editing the contents of the book **Electronic Nose Technologies and Advances in Machine Olfaction** Albastaki, Yousif Abdullatif,Albalooshi, Fatema,2018-04-13 The design and study of materials is a pivotal component to new discoveries in the various fields of science and technology By better understanding the components and structures of materials researchers can increase its applications across different industries Electronic Nose Technologies and Advances in Machine Olfaction is an academic scholarly resource that examines the emerging applications of odor sensing devices as well as a better understanding of the designing process with the aid of neural networks and various other technologies Featuring coverage on a broad range of topics including food spoilage detection chemical sensing and olfactometer this book is a vital resource for engineers academicians researchers students and practitioners seeking current research on the advancements in applications of odor sensing devices **Fuzzy Decision Making In Modeling And Control** Joao M Costa Sousa,Uzay Kaymak,2002-12-03 Decision making and control are two fields with distinct methods for solving problems and yet they are closely related This book bridges the gap between decision making and control in the field of fuzzy decisions and fuzzy control and discusses various ways in which fuzzy decision making methods can be applied to systems modeling and control Fuzzy decision making is a powerful paradigm for dealing with human expert knowledge when one is designing fuzzy model based controllers The combination of fuzzy decision making and fuzzy control in this book can lead to novel control schemes that improve the existing controllers in various ways The following applications of fuzzy decision making methods for designing control systems are considered Fuzzy decision making for enhancing fuzzy modeling The values of important

parameters in fuzzy modeling algorithms are selected by using fuzzy decision making Fuzzy decision making for designing signal based fuzzy controllers The controller mappings and the defuzzification steps can be obtained by decision making methods Fuzzy design and performance specifications in model based control Fuzzy constraints and fuzzy goals are used Design of model based controllers combined with fuzzy decision modules Human operator experience is incorporated for the performance specification in model based control The advantages of bringing together fuzzy control and fuzzy decision making are shown with multiple examples from real and simulated control systems

Essentials of Machine Olfaction and Taste Takamichi Nakamoto,2016-05-03 Essentials of Machine Olfaction and Taste This book provides a valuable information source for olfaction and taste which includes a comprehensive and timely overview of the current state of knowledge of use for olfaction and taste machines Presents original latest research in the field with an emphasis on the recent development of human interfacing Covers the full range of artificial chemical senses including olfaction and taste from basic through to advanced level Timely project in that mobile robots olfactory displays and odour recorders are currently under research driven by commercial demand

Constrained Dynamics Computations Bud Fox,Les S. Jennings,Albert Y. Zomaya,2000 This book introduces a practical approach to the modelling and computation of real world systems Multibody dynamics planar and spatial modelling and numerical methods are all pursued to obtain information about the behaviour of various dynamical systems Each study presents the method of modelling and the ensuing differential equations governing the system behaviour Integration of the equations yields results which are carefully discussed and which indicate how useful information may be obtained from the study The studies include planar mechanisms heavy equipment automobile crash simulation and a spatial planetary system example Research students scientists and engineers will appreciate the practical approach taken in this book

Wavelets In Soft Computing Marc Thuillard,2001-06-15 This book presents the state of integration of wavelet theory and multiresolution analysis into soft computing It is the first book on hybrid methods combining wavelet analysis with fuzzy logic neural networks or genetic algorithms Much attention is given to new approaches fuzzy wavelet that permit one to develop using wavelet techniques linguistically interpretable fuzzy systems from data The book also introduces the reader to wavelet based genetic algorithms and multiresolution search A special place is given to methods that have been implemented in real world applications particularly the different techniques combining fuzzy logic or neural networks with wavelet theory

Constrained Dynamics Computations: Models & Case Studies Bud Fox,Leslie Stephen Jennings,Albert Y Zomaya,2000-09-04 This book introduces a practical approach to the modelling and computation of real world systems Multibody dynamics planar and spatial modelling and numerical methods are all pursued to obtain information about the behaviour of various dynamical systems Each study presents the method of modelling and the ensuing differential equations governing the system behaviour Integration of the equations yields results which are carefully discussed and which indicate how useful information may be obtained from the study The studies include planar mechanisms

heavy equipment automobile crash simulation and a spatial planetary system example Research students scientists and engineers will appreciate the practical approach taken in this book

Wavelets In Soft Computing (Second Edition) Marc Thuillard,2022-09-09 The comprehensive compendium furnishes a quick and efficient entry point to many multiresolution techniques and facilitates the transition from an idea into a real project It focuses on methods combining several soft computing techniques fuzzy logic neural networks genetic algorithms in a multiresolution framework Illustrated with numerous vivid examples this useful volume gives the reader the necessary theoretical background to decide which methods suit his her needs New materials and applications for multiresolution analysis are added including notable research topics such as deep learning graphs and network analysis

Stochastic Models, Information Theory, and Lie Groups, Volume 2 Gregory S. Chirikjian,2011-11-15 This unique two volume set presents the subjects of stochastic processes information theory and Lie groups in a unified setting thereby building bridges between fields that are rarely studied by the same people Unlike the many excellent formal treatments available for each of these subjects individually the emphasis in both of these volumes is on the use of stochastic geometric and group theoretic concepts in the modeling of physical phenomena Stochastic Models Information Theory and Lie Groups will be of interest to advanced undergraduate and graduate students researchers and practitioners working in applied mathematics the physical sciences and engineering Extensive exercises motivating examples and real world applications make the work suitable as a textbook for use in courses that emphasize applied stochastic processes or differential geometry

Climbing and Walking Robots and the Support Technologies for Mobile Machines Phillippe Bidaud,Faiz Ben Amar,2002-11-08 Robotic technology advances for a wide variety of applications Climbing and Walking Robots and the Support Technologies for Mobile Machines explores the increasing interest in real world robotics and the surge in research and invention it has inspired Featuring the latest advances from leading robotics labs around the globe this book presents solutions for perennial challenges in robotics and suggests directions for future research With applications ranging from personal services and entertainment to emergency rescue and extreme environment intervention the groundbreaking work presented here provides a glimpse of the future

Autonomous Mobile Robots Rahul Kala,2023-09-01 Autonomous Mobile Robots Planning Navigation and Simulation presents detailed coverage of the domain of robotics in motion planning and associated topics in navigation This book covers numerous base planning methods from diverse schools of learning including deliberative planning methods reactive planning methods task planning methods fusion of different methods and cognitive architectures It is a good resource for doing initial project work in robotics providing an overview methods and simulation software in one resource For more advanced readers it presents a variety of planning algorithms to choose from presenting the tradeoffs between the algorithms to ascertain a good choice Finally the book presents fusion mechanisms to design hybrid algorithms Presents intuitive and practical coverage of all sub problems of mobile robotics to enable easy comprehension of sophisticated modern day robots Covers a

wide variety of motion planning algorithms giving a near exhaustive treatment of the domain with thought provoking comparisons between algorithms Dives into detailed discussions on robot operating systems and other simulators to get hands on knowledge without the need of in house robots **Field and Service Robotics** Alexander Zelinsky,2012-12-06 Joe Engelberger the pioneer of the robotics industry wrote in his 1989 book *Robotics in Service* that the inspiration to write his book came as a reaction to an industry sponsored forecast study of robot applications which predicted that in 1995 applications of robotics outside factories the traditional domain of industrial robots would amount to less than 1% of total sales Engelberger believed that this forecast was very wrong and instead predicted that the non industrial class of robot applications would become the largest class Engelbergers prediction has yet to come to pass However he did correctly foresee the growth in non traditional applications of robots Robots are now beginning to march from the factories and into field and service applications This book presents a selection of papers from the first major international conference dedicated to field and service applications of robotics This selection includes papers from the leading research laboratories in the world together with papers from companies that are building and selling new and innovative robotic technology It describes interesting aspects of robots in the field ranging from mining agriculture construction cargo handling subsea operations removal of landmines to terrestrial exploration It also covers a diverse range of service applications such as cleaning propagating plants and aiding the elderly and handicapped and gives considerable attention to the technology required to realise robust reliable and safe robots **Handbook of Machine Olfaction** Tim C. Pearce,Susan S. Schiffman,H. Troy Nagle,Julian W. Gardner,2006-01-24 Electronic noses are instruments which mimic the sense of smell Consisting of olfactory sensors and a suitable signal processing unit they are able to detect and distinguish odors precisely and at low cost This makes them very useful for a remarkable variety of applications in the food and pharmaceutical industry in environmental control or clinical diagnostics and more The scope covers biological and technical fundamentals and up to date research Contributions by renowned international scientists as well as application oriented news from successful e nose manufacturers give a well rounded account of the topic and this coverage from R D to applications makes this book a must have read for e nose researchers designers and users alike **Distributed Autonomous Robotic Systems 8** Hajime Asama,Haruhisa Kurokawa,Jun Ota,Kosuke Sekiyama,2009-05-15 The International Symposia on Distributed Autonomous Robotic Systems DARS started at Riken Japan in 1992 Since then the DARS symposia have been held every two years in 1994 and 1996 in Japan Riken Wako in 1998 in Germany Karlsruhe in 2000 in the USA Knoxville TN in 2002 in Japan Fukuoka in 2004 in France Toulouse and in 2006 in the USA Minneapolis MN The 9th DARS symposium which was held during November 17 19 in T kuba Japan hosted 84 participants from 13 countries The 48 papers presented there were selected through rigorous peer review with a 50% acceptance ratio Along with three invited talks they addressed the spreading research fields of DARS which are classifiable along two streams theoretical and standard studies of DARS and

interdisciplinary studies using DARS concepts The former stream includes multi robot cooperation task assignment methodology among multiple robots multi robot localization etc swarm intelligence and modular robots The latter includes distributed sensing mobiligence ambient intelligence and mul agent systems interaction with human beings This book not only offers readers the latest research results related to DARS from theoretical studies to application oriented ones it also describes the present trends of this field With the diversity and depth revealed herein we expect that DARS technologies will flourish soon

Neuromorphic Olfaction Krishna C. Persaud, Santiago Marco, Agustin Gutierrez-Galvez, 2016-04-19 Many advances have been made in the last decade in the understanding of the computational principles underlying olfactory system functioning Neuromorphic Olfaction is a collaboration among European researchers who through NEUROCHEM Fp7 Grant Agreement Number 216916 a challenging and innovative European funded project introduce novel computing paradigms and biomimetic artifacts for chemical sensing The implications of these findings are relevant to a wide audience including researchers in artificial olfaction neuroscientists physiologists and scientists working with chemical sensors Developing neuromorphic olfaction from conceptual points of view to practical applications this cross disciplinary book examines The biological components of vertebrate and invertebrate chemical sensing systems The early coding pathways in the biological olfactory system showing how nonspecific receptor populations may have significant advantages in encoding odor intensity as well as odor identity The redundancy and the massive convergence of the olfactory receptor neurons to the olfactory bulb A neuromorphic approach to artificial olfaction in robots Reactive and cognitive search strategies for olfactory robots The implementation of a computational model of the mammalian olfactory system The book s primary focus is on translating aspects of olfaction into computationally practical algorithms These algorithms can help us understand the underlying behavior of the chemical senses in biological systems They can also be translated into practical applications such as robotic navigation and systems for uniquely detecting chemical species in a complex background

Applications of Intelligent Systems N. Petkov, N. Strisciuglio, C.M. Travieso-González, 2018-12-21 The deployment of intelligent systems to tackle complex processes is now commonplace in many fields from medicine and agriculture to industry and tourism This book presents scientific contributions from the 1st International Conference on Applications of Intelligent Systems APPIS 2018 held at the Museo Elder in Las Palmas de Gran Canaria Spain from 10 to 12 January 2018 The aim of APPIS 2018 was to bring together scientists working on the development of intelligent computer systems and methods for machine learning artificial intelligence pattern recognition and related techniques with an emphasis on their application to various problems The 34 peer reviewed papers included here cover an extraordinarily wide variety of topics everything from semi supervised learning to matching electro chemical sensor information with human odor perception but what they all have in common is the design and application of intelligent systems and their role in tackling diverse and complex challenges The book will be of particular interest to all those involved in the development and application of intelligent systems

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