## 5 Work and Energy

#### POWER

1.	d	5.	¢
2.	d	6	a
3.	C	7.	b
44.	C	8.	d

- 9. Power measures the amount of energy that is transferred from one object to another or transformed to other forms of energy in a given time interval.
- 10, 220 kW

Gioen.  $F = 29 \text{ kN} = 2.9 \times 10^4 \text{ N}$ w = 7.5 mo/sSoduttion.  $P = Fv = (2.9 \times 10^4 \text{ N})(7.5 \text{ m/s}) =$  $2.2 \times 10^5 \text{ W} = [220 \text{ kW}]$ 

## 6 Momentum and Collisions

#### MOMENTUM AND IMPULSE

1. b	5. b
2. c	6. c
3. a	7. c
4. c	8. d

- 9. Impulse is the product of the force acting on an object and the time interval in which the force acts on an object. The impulse-momentum theorem states that the impulse on an object is equal to the change in the object's momentum.
- 10, 9.0 × 10° kg•m/s Giometric.  $m = 1.0 \times 10^4 \text{ kgr}$  $v_{\rm c} = 1.2 \times 10^3 \, {\rm m/s}$  $F = -25 \text{ kN} = 2.5 \times 10^4 \text{ N}$  $\Delta t = 2.0 \text{ min} = 120 \text{ s}$ Solution  $p_A \leftarrow prese_V \rightarrow$  $(1.0 \times 10^4 \text{ kg})(1.2 \times 10^3 \text{ m/s}) =$  $1.2 \times 10^7 \text{ kg} \cdot \text{m/s}$  $F\Delta t = \Delta p = p_T - p_L$  $p_{\ell} = F\Delta t + p_{\ell}$  $p_f = (-2.5 \times 10^4 \text{ N})(120 \text{ s}) +$  $(1.2 \times 10^7 \text{ kg} \cdot \text{m/s}) =$  $9.0 \times 10^6 \, \mathrm{kg} \cdot \mathrm{m/s}$

# 6 Momentum and Collisions

#### CONSERVATION OF MOMENTUM

1. d	5. d
2. c	6. c
3. b	7. d
4. d	8. c

- 9. The magnitude of the momentum of the slower ball increases, while the magnitude of the momentum of the faster ball decreases by the same amount. Both balls reverse direction in the collision. The total momentum of the system does not change.
- TO.

1.9 m/s
Géven
$m_I = 55 \text{ kg}$
$v_{I,i} = 2.0 \text{ na/s}$
$m_Z = 2.0 \text{ kg}$
$v_{2,4} = 0 \text{ m/s}$
$v_{1,f} = v_{2,f}$
Solution
$m_I v_{I,i} + m_Z v_{Z,i} = m_I v_{I,f} + m_Z v_{Z,f}$
$m_I v_{I,i} = m_I v_{I,f} + m_2 v_{I,f}$
$m_I v_{I,i} = (m_I + m_2)v_{I,f}$
$m_I v_{I,I}$
$v_{I,J} = \frac{m_I c_{I,J}}{(m_I + m_Z)}$

# 6 Momentum and Collisions ELASTIC AND INFLASTIC COLLISIONS

 $v_{I,f} = \frac{(55 \text{ kg})(2.0 \text{ m/s})}{(55 \text{ kg} + 2.0 \text{ kg})} = 1.9 \text{ m/s}$ 

	ACTOR IN CO., Name of Street, or other Party	THE RESERVE OF THE
10		5. d
2.	ь	6. a
3.	as a	7. b
4.	ь	8. d

- 9. An inelastic collision is any collision in which some kinetic energy is converted to other forms of energy so that the total kinetic energy is not conserved. A perfectly inelastic collision is a special case in which the objects in the collision stick together and move as a single object after the collision.
- 10, 1.2 m/s to the right Giasca  $m_{\rm F} = 0.16 \, \mathrm{kgr}$

 $v_{I,i} = 1.2 \text{ m/s}$  $m_{zz} = 0.16 \text{ kg}$  $w_{r,i} = -0.85 \text{ m/s}$  $v_{JJ} = -0.85 \text{ m/s}$ 

# One Dimensional Momentum And Collision Worksheet Answers

John D. Cutnell, Kenneth W.
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web jul 10 2015 answers 1 there are many different ways to detect and track moving objects kalman filter does assume either a constant velocity or a constant acceleration motion model however it also assumes system noise which is a way to

account for the fact that the actual motion of an object does not exactly fit your model **detection and tracking matlab simulink mathworks** - Sep 04 2022

web object tracking consists of assigning a unique id to detected objects and tracking their movement across point cloud frames lidar toolbox includes detection and tracking workflows for vehicles road lanes and curbs multiple object tracking tutorial matlab simulink mathworks - Jun 13 2023

web moving object detection and motion based tracking are important components of automated driver assistance systems such as adaptive cruise control automatic emergency braking and autonomous driving you can divide motion based object tracking into two parts detecting moving objects in each frame tracking the moving objects from