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web block diagram showing receiver of a pick n place robot the system consists of two motors for providing motion to the whole robot and two other motors to provide the arm motion the end effector or the gripper needs to be controlled to apply proper pressure on the object to handle it effectively to give it a soft grip

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web based on the user commands the robot moves and pick and place the objects the robotic arm used here is similar to a human arm which is programmed to perform the pick and place functions the remainder of this paper is organized as follows the section 2 provides information about the existing works section 3 gives details of the proposed

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